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Design of an Accessible Autonomous Vehicle for All

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1. AIM

Identify design principles that would lead to a universal **Autonomous Vehicle (AV)** to be accessible to as many users as possible, including People with Disabilities (PwDs) and understand **needs, challenges, opportunities, requirements, and expectations** to provide AV design recommendations for an Australian context.

2. METHODOLOGY

Study One: Online survey with PwDs (n=344) to gain insight on demographics, preferences, challenges, needs and perspectives on current transport use and future AVs in Australia.

- PwDs willing to use AVs as public / shared system than owning the vehicle (Figure 1&2)
- There is a desire to have an attendant present on a public or shared AV (Figure 3)
- Majority of PwDs positive about AV technologies as mode of transportation (Figure 4).

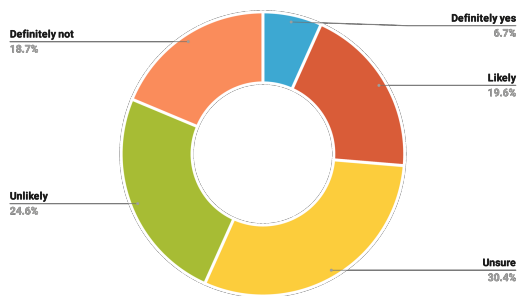


Figure 1. Willingness to use public/shared AV

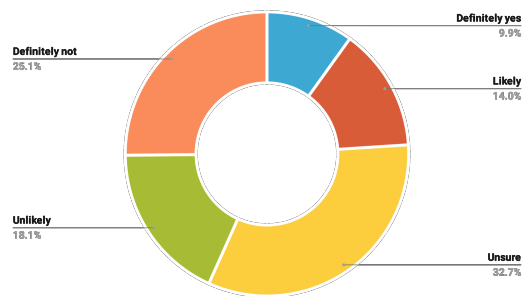


Figure 2. Desire to own an AV

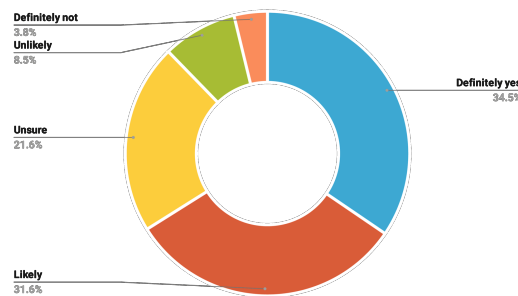


Figure 3. Desire for trained attendant on AV

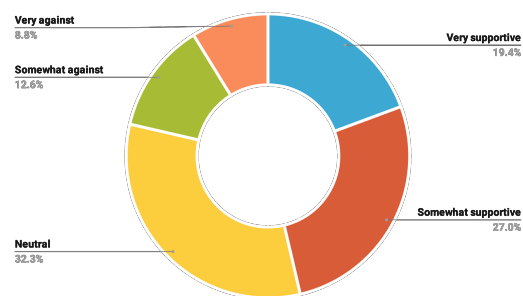


Figure 4. Feelings towards AV technology

Study Two: Semi-structured interview and workshop with transdisciplinary group of 5 experts on the challenges, opportunities and limiting factors in the design / implementation of Accessible AV technology in Australia. Findings formed a complex system of relationships within three domains:

- **High frequency:** high conversational occurrence (e.g. Seating)
- **High relational:** low conversational occurrence but high topic relevance (e.g. Risk).
- **Limiting factor:** high conversational or relational seen as limiting factors (e.g. Cost).

Ideal design factors cannot be discussed without addressing its relationship with, and impact on, other aspects. Several limiting factors were identified that would dictate the success of implementation, such as regulations, the associated costs or the gaps in anthropometric data. Figure 5 summarises findings from Study Two.

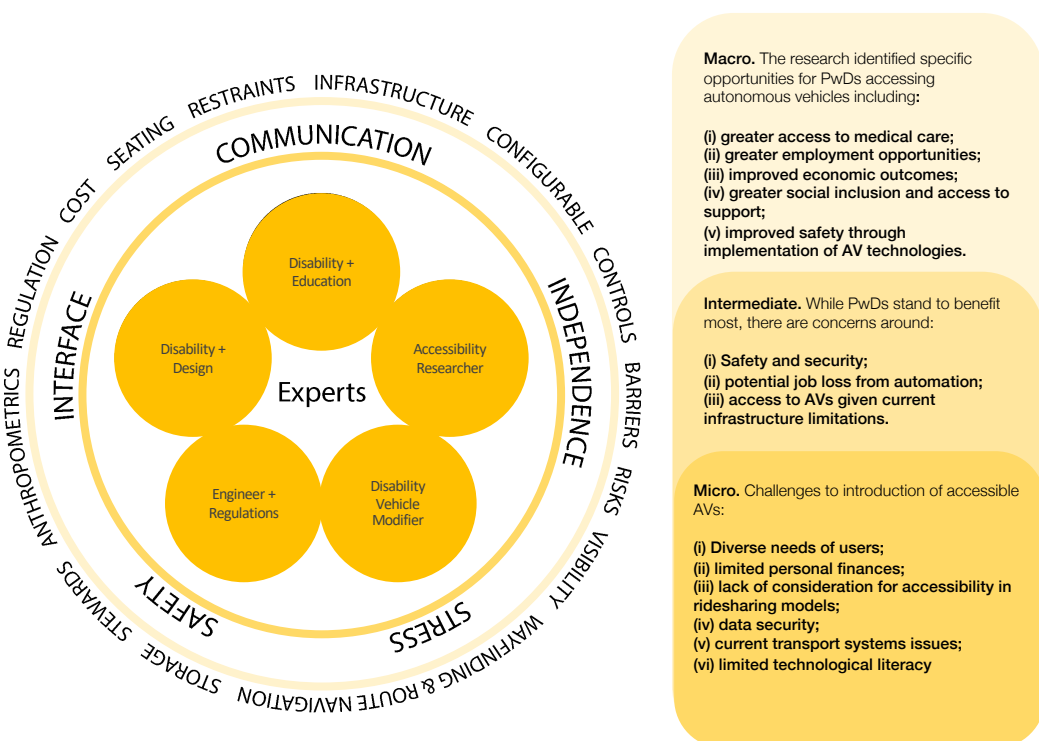


Figure 5. (Left) Study Two summary including experts interviewed (inner circles), parent themes (middle circle) and child themes (outer circle) and (Right) Findings identified at the micro (person/vehicle), Intermediate (community/infrastructure), and Macro (social/urban) scales.

3. PRACTICAL OUTCOMES

The potential outcomes from this research include implications, suggestions, and recommendations at three levels (Figure 6).

- **Vehicle:** (i) Interior dimensions, layouts, and configurability; (ii) Door dimensions and access; (iii) Seat restraints, dimensions and layout; (iv) Storage options; and (v) Interface and controls.
- **Vehicle / Context:** (i) Stewards and attendant recommendations; (ii) Road infrastructure requirements; (iii) Service, access and cost; (iv) Data security; (v) Personal safety; (vi) Route navigation; and (vii) Visibility.
- **Context:** (i) Regulation requirements; (ii) AV implementation; (iii) Urban / city infrastructure gap; (iv) Technology gap; and (v) Social acceptance.

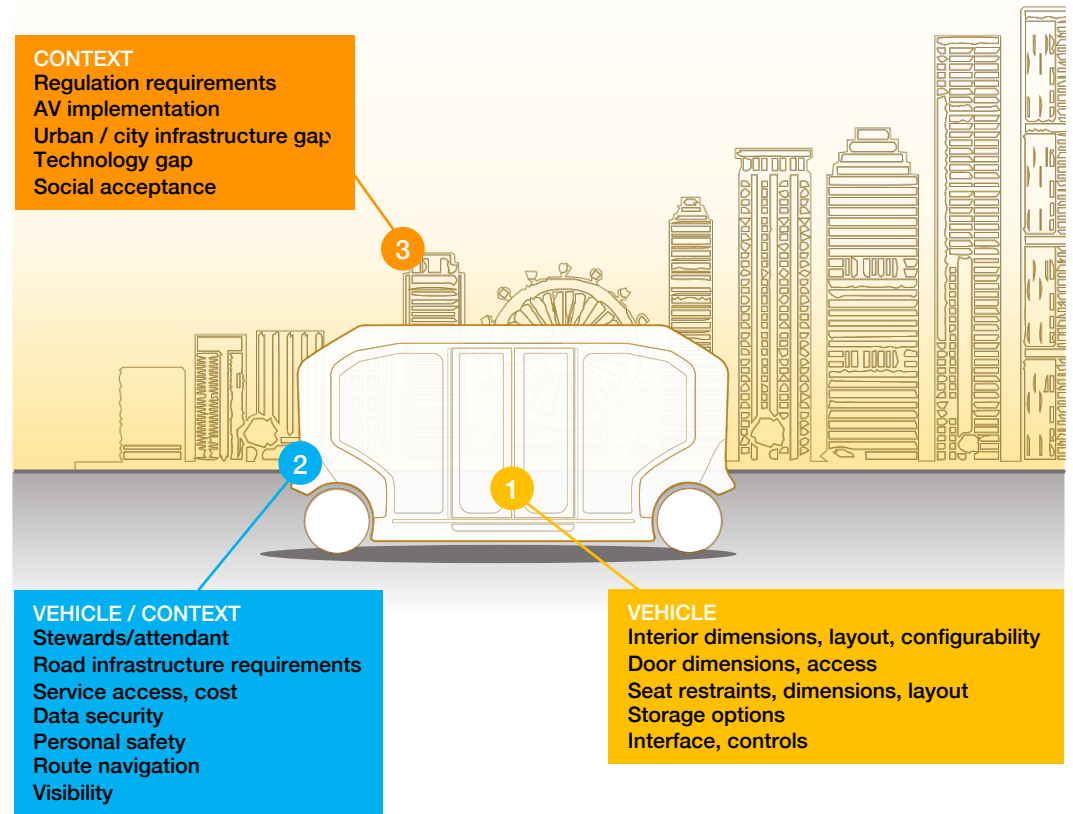


Figure 6. Practical outcomes from the overall research across vehicle design; vehicle / context interface and context levels.

4. FUTURE WORK

The research completed to date is Phase 1 of 3. The goal is to develop, test and establish design principles for future AV designs specifically targeting the needs of PwDs in the Australian context.

Phase 2:

- Conduct benchmarking on existing AV prototypes and concepts.
- Develop and validate an initial AV concept that incorporates findings from Phase 1.

Phase 3:

- Build a 1:1 prototype of the AV concept developed in Phase 2.
- Test and validate the prototype with PwDs and other users.
- Deliver tested and validated design principles for the design of future AVs for PwDs in Australian context.

It is envisioned this project will positively impact mobility for PwDs and all other users by:

- Improving the design of AVs (e.g. communication, interface, seating, layout);
- Establishing design principles for AVs in Australian context;
- Increasing access to healthcare, job opportunities and economic outcomes;
- Improving safety for PwDs in transport experience;
- Ensuring the spectrum of PwD needs are considered; and
- Provide independence and increase overall access of AVs



Figure 7. Two vehicles used as benchmark for Phase 2. (Left) Rinspeed Metrosnap and (Right) Auvetech Autonomous Vehicle concept.